

Research on an efficient preconditioner using GMRES method for the MOC

Satoshi Takeda ^a, Michael A. Smith ^b, Takanori Kitada ^a

^aDivision of Sustainable Energy and Environmental Engineering, Osaka Univ. 1-1 Yamadaoka, Suita, Osaka, Japan ,
^bArgonne National Laboratory., Nuclear Engineering Division.9700 South Cass Ave. IL 60439-4842, USA,

s-takeda@ne.see.eng.osaka-u.ac.jp

1. Introduction

The modeling accuracy of reactor analysis techniques has improved considerably with the progressive improvements in computational capabilities. The method of characteristics (MOC) solves the neutron transport equation using tracking lines which simulates the neutron paths. The MOC is an accurate calculation method and is becoming a major solver because of the rapid advancement of the computer. In this methodology, the transport equation is discretized into many spatial meshes and energy wise groups. And the discretization generates a large system which needs a lot of computational costs.

To reduce computational costs of MOC calculation, we investigate the Generalized Minimal RESidual (GMRES) method as an accelerator and developed an efficient preconditioner for the MOC calculation. The preconditioner we developed was made by simplifying rigorous preconditioner. And the efficiency was verified by comparing the number of iterations which is calculated by one dimensional MOC code.

2. Methods

2.1 Discretization of one dimensional MOC

The multigroup transport equation to obtain the flux from an isotropic source, within a region i and energy group g , is

$$\frac{d}{ds} \phi_g^i + \Sigma_{t,g}^i \phi_g^i = Q_g^i, \quad (1)$$

where ϕ_g^i is the neutron angular flux in group g ; $\Sigma_{t,g}^i$ is the total cross section in group g ; s stands for the variable along the tracking line. The total source in Eq.(1) is composed of two terms: the within group source and outgroup source:

$$Q_g^i = W_g^i + S_g^i, \quad (2)$$

where

$$W_g^i = \Sigma_{s,g \rightarrow g}^i \phi_g^i, \\ S_g^i = \sum_{g', g' \neq g} \Sigma_{s,g' \rightarrow g}^i \phi_{g'}^i + \sum_{g'} \nu \Sigma_{f,g'}^i \phi_{g'}^i / K_{eff},$$

where ϕ_g^i is the neutron scalar flux in group g ; $\Sigma_{s,A \rightarrow B}^i$ is the scattering cross section from group A to B. For a fixed direction, the equation is solved numerically:

$$\phi_{n,g}^{i,out} = \phi_{n,g}^{i,in} e^{-\Sigma_{t,g}^i \Delta s^i} + \frac{1 - e^{-\Sigma_{t,g}^i \Delta s^i}}{\Sigma_{t,g}^i} Q_g^i, \quad (3)$$

where $\phi_{n,g}^{i,out}$ and $\phi_{n,g}^{i,in}$ are the incoming and the outgoing angular flux respectively. And $n(=1 \dots N)$ shows the number of direction of neutron travel.

Discretized MOC system can be written in a form as

$$(\mathbb{I} - \mathbb{L}^{-1} \mathbb{W}) \vec{\Phi} = \mathbb{L}^{-1} \mathbb{S}, \quad (4)$$

where

- $\vec{\Phi}$: the vector which is composed of region scalar fluxes.
- \mathbb{I} : identity matrix.
- \mathbb{L}^{-1} : sweeping matrix.
- \mathbb{W} : within group scattering cross section matrix.
- \mathbb{S} : out group source matrix.

2.2 GMRES method

The GMRES algorithm is commonly used to solve large nonsymmetric linear system of equation $Ax = b$. This method makes an orthonormal basis $V = [v_1, v_2, \dots, v_l]$ in Krylov subspace by using the Arnoldi process. A brief summary of the algorithm is given in Figure 1. In this paper, several preconditioners were investigated and the results were shown in the following section.

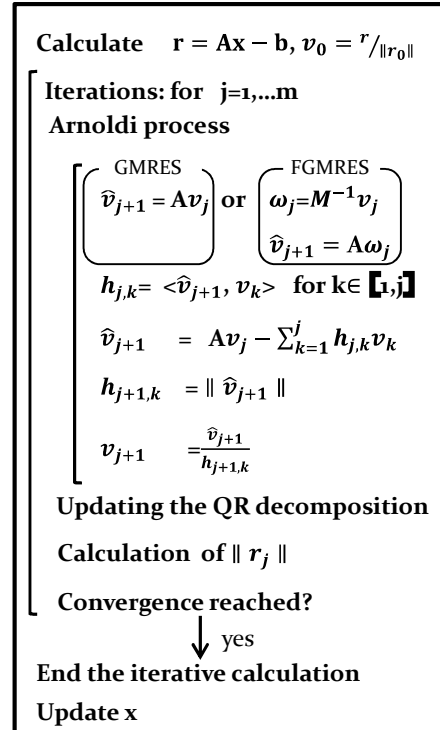


Figure 1 GMRES and FGMRES algorithm

